

Motor::setCurrPulse



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graph LR; A[Motor::setCurrPulse] --> B[Motor::getCurrPulse]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'Motor::setCurrPulse'. The right box is white and contains the text 'Motor::getCurrPulse'. A blue arrow points from the right side of the gray box to the left side of the white box.

Motor::getCurrPulse