

GearedMotor::getPosition

```
graph LR; A[GearedMotor::getPosition] --> B[Motor::getCurrPulse]; A --> C[GearedMotor::getRatio];
```

The diagram illustrates a function call sequence. A central box labeled 'GearedMotor::getPosition' has two arrows pointing to the right. The top arrow points to a box labeled 'Motor::getCurrPulse', and the bottom arrow points to a box labeled 'GearedMotor::getRatio'.

Motor::getCurrPulse

GearedMotor::getRatio